

K-ε Model: Overview and Fisher equation

- Overview:

→ Reaction and diffusion system:

$$\partial_t \epsilon = D \nabla^2 \epsilon + f(\epsilon)$$

\uparrow \uparrow
 Diffusion Reaction

→ Turbulence spreading

- "Minimal problem": propagation of a patch of turbulence

from a region where is locally excited to a region of weaker excitation or even local damping.

$$\frac{\partial \epsilon}{\partial t} - \frac{\partial}{\partial x} D(\epsilon) \frac{\partial \epsilon}{\partial x} = \underbrace{\gamma(x) \epsilon - \gamma_{NL} \epsilon^2}_{\text{Reaction}}$$

\uparrow \uparrow
 Diffusion Reaction
 $D(\epsilon) \sim \epsilon$

- (Above equation) looks like a Fisher equation:

Indicates a ballistically expanding front, $c \sim (\gamma D)^{1/2}$

- Derivation

→ Local excitation/damping + Non-local transition ($T(\Delta x, \Delta t)$)

→ Step size $\Delta x, \Delta t$: radial couplings to mesoscales

→ A Fokker-Planck model of turbulence intensity $\varepsilon(x, t)$

$$\varepsilon(x, t + \Delta t) = \varepsilon(x, t) + [\gamma(x)\varepsilon(x) - \gamma_{NL}\varepsilon^{\alpha}(x)]\Delta t + \int d(\Delta x) T(x, \Delta x, \Delta t) \varepsilon(x - \Delta x, t)$$

$\gamma(x)$: Local excitation / growth rate

$\gamma_{NL}(x)$: Local nonlinear damping rate. = $\gamma_{NL}\varepsilon^{\alpha}(x)$, $\frac{1}{2} < \alpha < 1$

Weak turbulence $\leftrightarrow \alpha \sim 1$

Strong turbulence $\leftrightarrow \alpha \sim \frac{1}{2}$

$T(x, \Delta x, \Delta t)$: Transition probability. $\Delta x > \Delta x_c, \Delta t > \Delta t_c$
Step size.

Moments of T : $\int d(\Delta x) T = 1 \quad \leftrightarrow$ conservation of prob.

$$\int d(\Delta x) T \Delta x = \langle \Delta x \rangle$$

$$\int d(\Delta x) T (\Delta x)^2 = \langle \Delta x^2 \rangle$$

Wave population density is conserved along ray trajectory.

$$\Rightarrow \frac{\partial N}{\partial t} + (\underline{v}_{gr} + \underline{v}) \cdot \nabla N - \frac{\partial}{\partial x} (\omega + \underline{k} \cdot \underline{v}) \cdot \frac{\partial N}{\partial \underline{k}} = \gamma_{nc} N$$

$$\frac{dx}{dt} = \underline{v}_{gr} + \underline{v}, \quad \frac{dk}{dt} = - \frac{\partial}{\partial x} (\omega + \underline{k} \cdot \underline{v})$$

} Non-population density
conserving processes

\underline{v}_{gr} : wave group velocity

\underline{v} : local flow velocity

$$\frac{dx}{dt} = \underline{v}_{gr} + \langle \underline{v}_r \rangle + \delta \underline{v}_r$$

fluctuating flow.

radial group velocity

mean radial flow

$$D = \int_{-\infty}^{\infty} d\tau \langle \delta v_r(t) \delta v_r(\tau) \rangle \cong D_0 \epsilon^\alpha$$

Assume: No large scale coherent flow is present.

\Downarrow

Neglect $\langle \underline{v}_r \rangle$

\Downarrow

$$V_\epsilon = v_{gr} + v_{drift}, \quad v_{drift} = \frac{\partial}{\partial x} (D_0 \epsilon^\alpha)$$

\Downarrow

$$\left. \begin{aligned} V_\epsilon &= v_{gr} + \frac{\partial}{\partial x} (D_0 \epsilon^\alpha) \\ D_\epsilon &= D_0 \epsilon^\alpha \end{aligned} \right\}$$

Plug V_ϵ , D_ϵ into the F-P eqn.

$$\frac{\partial \xi}{\partial t} + \frac{\partial}{\partial x} (v_{gr} \xi) - \frac{\partial}{\partial x} D_0 \xi^\alpha \frac{\partial \xi}{\partial x} = (\gamma(x) - \delta_{NL} \xi^\alpha) \xi$$

The effect of v_{gr} can be cancelled by a Galilean transformation.

Thus for the case $\gamma = \text{const}$, $\delta_{NL} = \text{const}$, $D_0 = \text{const}$, $\alpha = 1$

$$\text{re-scale : } x \rightarrow (\delta_{NL}/2D_0)^{1/2} x, \quad t \rightarrow \gamma t$$

$$\xi \rightarrow (\delta_{NL}/\gamma) \xi$$

The above eqn becomes

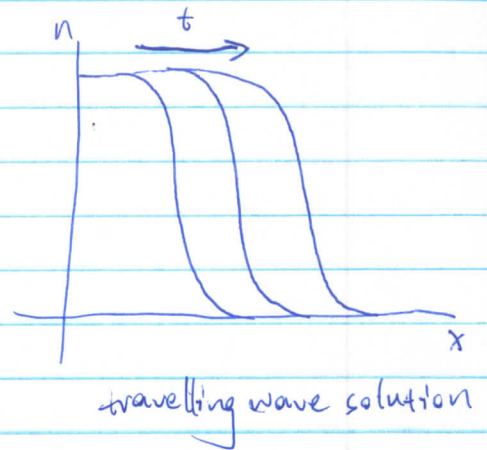
$$\frac{\partial \xi}{\partial t} - \frac{1}{4} \frac{\partial^2}{\partial x^2} \xi^2 - \xi(1-\xi) = 0$$



Variant of Fisher - Kolmogorov - Petrovski - Piskunov (Fisher-KPP) eqn.

Proto-type of Fisher-KPP eqn:

$$\frac{\partial n}{\partial t} - D \partial_x^2 n = \gamma n(1-n)$$



For the wave tip where $n \sim \tilde{n} \ll 1$

$$\frac{\partial \tilde{n}}{\partial t} - D \partial_x^2 \tilde{n} = \gamma \tilde{n}$$

Impose $\tilde{n} = \tilde{n}(x-ct)$, it becomes

$$-c \frac{\partial \tilde{n}}{\partial x} - D \frac{\partial^2 \tilde{n}}{\partial x^2} = \gamma \tilde{n}$$

$$\tilde{n} \sim n_0 \exp[-\alpha(x-ct)]$$

$$\Rightarrow \alpha c \tilde{n} - D \alpha^2 \tilde{n} = \gamma \tilde{n}$$

$$\alpha = \frac{c}{2D} \pm \frac{1}{2} \left(\frac{c^2}{D^2} - \frac{4\gamma}{D} \right)^{\frac{1}{2}}$$

$$c_{\min} = 2(\gamma D)^{\frac{1}{2}} \quad \Leftrightarrow \text{selected speed}$$

Faced with "Speed Selection"!

$$\boxed{c < c_{\min}} \Rightarrow \alpha \text{ is complex, } \bullet \text{ the front oscillates } \Rightarrow \boxed{\text{unstable}}$$

$$\text{So } c \geq c_{\min}$$

Further, would all fronts with speeds $c \geq c_{\min}$ survive? No!

Front speed is selected according to the steep stiffness of the

initial condition, $\tilde{u}(x, 0) = e^{-\lambda x}$, λ : steep stiffness

Many have discussed about front stability of Fisher-KPP equ.

We use the results by M. R. Evans,

① If the initial profile decays faster than $\tilde{u}(x, 0) \sim e^{-\alpha_{\min} x}$,

where $\alpha_{\min} = \frac{c_{\min}}{2D}$ (which also means $\lambda > \alpha_{\min}$)

then wave travels at $c_{\min} = 2(\gamma D)^{\frac{1}{2}}$.

② If the initial profile decays less steeply, $\lambda < \alpha_{\min}$,

then wave travels at a faster speed $v(\lambda) = D\lambda + \frac{\gamma}{\lambda}$

In the case of turbulence spreading, here we assume the front

is steep. Thus, fronts travel at $c_{\min} = 2(\gamma D)^{\frac{1}{2}}$

Go back to the Fokker-Planck model, neglecting ~~the~~ effect of v_{gr} .

$$\frac{\partial \epsilon}{\partial t} - \frac{\partial}{\partial x} D_0 \epsilon \frac{\partial \epsilon}{\partial x} = \gamma \epsilon - \gamma_{NL} \epsilon^2.$$

Argue $\epsilon \sim \frac{\gamma}{\gamma_{NL}}$, using Fisher-KPP's conclusion.

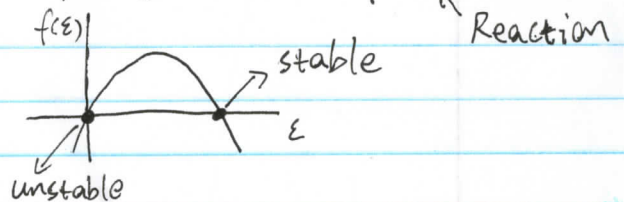
where $D \sim D_0 \epsilon \sim D_0 \frac{\gamma}{\gamma_{NL}}$ $c_{eff} \sim 2(\gamma D)^{\frac{1}{2}} \sim 2 \left(\frac{D_0 \gamma^2}{\gamma_{NL}} \right)^{\frac{1}{2}}$

↑
Turbulence spreading speed.

- From Fisher to Fitzhugh-Nagumo, $\partial_t \epsilon - D \nabla^2 \epsilon = f(\epsilon)$ ← Reaction

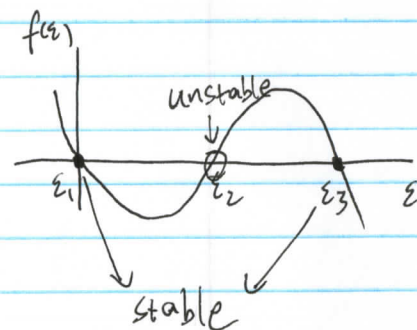
→ Fisher: unistable

$$f(\epsilon) = \gamma \epsilon - \gamma_{NL} \epsilon^2$$



→ Nagumo: bi-stable

$$f(\epsilon) = A(\epsilon - \epsilon_1)(\epsilon_2 - \epsilon)(\epsilon - \epsilon_3)$$



References:

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[2] J. Venegas-Ortiz, R.J. Allen and Martin R. Evans,
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